

HANDLING & GRIPPERS

Production Program

















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Handling &

Grippers

TAS

30° Angular grippers

• Simple structure for high stability.



TAP

180° Angular grippers

- High gripping forces achieved via internal cams, so required offset is reduced.
- Reference points on gripping fingers.
- Compact design.

TAS			Val	ues/Descript	ion			
Technology				Lever				
Acting type		Double acting / Single acting (N.O.)						
Tube [mm]	12	16	20	25	32			
Max arm length [mm	30	40	60	70	85			
Operating pressure	Double acting			0.15÷0.7/1.5÷7				
range [MPa]/[bar]	Single acting	0.3÷0.7/3÷7	3÷0.7/3÷7 0.2÷0.7/2÷7					
Max effective grippir (for the largest bore)				0.17				
Clamp/Release angle	•			-10°÷+30°				
Body			Hard a	anodized alun	ninium			
Fingers			Me	dium carbon :	steel			
				3.7				

TAP		Values/Description								
Technology			Le	ver						
Acting type			Double	e acting						
Tube [mm]		10	16	20	25					
Effective torque (at	5 MPa) [Nm]	0.16 0.54 1.1								
Operating pressure	range [MPa]/[bar]	0.2÷0.6/2÷6								
Operating angle	Opened side	180°÷182°								
(both sides)	Closed side		-	3°						
Body			Hard anodize	ed aluminium						
Fingers		Stainless steel								
Magnet			Y	es						

2-finger parallel grippers

repositioning.

• High rigidity, high precision.

• Bottom pin holes for accurate

· Bottom, side, front fixing hole.

TPB

Linear guide

6 10 16 20 25 32 40

254

Hard anodized aluminium

Martensitic stainless steel Standard, Standard-side tapped, Standard-through hole, Flat, Narrow, Narrow-side tapped, Narrow-through hole

Double acting / Single acting

4 (8) 6 (12) 10 (18) 14 (22) 22 30

parallel grippers | 2-finger

TPA



Technology Acting type

Tube [mm]

Body

Fingers

Stroke [mm]

Operating pressure range [MPa]/[bar]

Max external effective gripping force [N]

inger parallel grippers	
	0
	0

parallel grippers | 2-finge

TPA			Valu	es/Descrip	tion			
Technology				Lever				
Acting type		Double acting / Single acting						
Tube [mm]		12	16	20	25	32		
Max arm length [mm	30	40	60	70	85			
Stroke [mm]		6	8	12	14	16		
Operating pressure	Double acting	0.15÷0.7/1.5÷7						
range [MPa]/[bar]	Single acting			0.2÷0.7/2÷7				
Max external effective	ve gripping force [N]			120				
Body			Hard a	nodized aluı	minium			
Fingers		Carbon steel						
Magnet				Yes				

parallel grippers | 2-finger

TPD

2-finger parallel grippers

- Rack and pinion mechanism.
- Extra-stroke compared to standard grippers.

Double acting

0.3÷0.7/3÷7

Steel alloy

Hard anodized aluminium

25

3 mounting directions available.



Technology

Acting type

Tube [mm]

Body

Fingers

Fingers range

Stroke (long version)

Operating pressure range [MPa]/[bar] Single acting

Max external effective gripping force [N]

TPC

2-finger parallel grippers

• High rigidity, high precision.

Double acting 0.15÷0.7/1.5÷7 0.2÷0.7/2÷7 0.1÷0.7/1÷7

- Bottom pin holes for accurate repositioning.
- Bottom, side, front fixing hole.
- Silicon dust cover

TPC	Values/Description							
Acting type	Double acting Single acting							
Tube [mm]	16							
Stroke [mm]	6							
Operating pressure range [MPa]/[bar]	0.1÷0.7/1÷7	0.25÷0.7/2.5÷7						
Max external effective gripping force [N]	30							
Body	Hard anodiz	ed aluminium						
Fingers	Martensitic :	stainless steel						
Cover	Food-gra	ade silicon						
Magnet	Y	'es						

TPE

2-finger parallel grippers

• Flat profile design saves space and reduces bending moments.

parallel grippers | 2-finger

- Using linear ball bearing.
- Dual-piston for higher gripping force.



TPD					Value	es/De	escri	ption				
Technology	Linear guide, Pinion, Rack, Dual-piston											
Acting type	Double acting											
Tube [mm]	8				12			16			20	
Stroke [mm]	8	16	32	12	24	48	16	32	64	20	40	80
Operating pressure range [MPa]/[bar]	0.15	÷0.7/1	1.5÷7				0.1	1÷0.7/	1÷7			
Max external effective gripping force [N]						14	40					
Body				Ha	ard ar	nodize	ed alı	ımini	um			
Fingers / Jaws	Stainless steel											
Magnet						Y	'es					

TPH

- 2-finger parallel grippers
- Wide range of strokes.
- Dual-piston for higher gripping force.
- Synchronized jaw movement.
- Dust-proof design.



Acting type

Tube [mm]

Body

Stroke [mm]

Fingers / Jaws

TPH		Values/Description																
Technology		Dual-piston																
Acting type		Double acting																
Tube [mm]		10			16			20			25			32			40	
Stroke [mm]	20	40	60	30	60	80	40	80	100	50	100 1	20	70	120	160	100	160	200
Operating pressure range [MPa]/[bar]		0.2÷0.6/2÷6																
Max external effective gripping force [N]									4	10								
Body							Har	d an	odize	ed al	umini	ım						
Fingers / Jaws									Alum	niniu	m							
Magnet									Υ	'es								

TPL

Operating pressure range [MPa]/[bar] 0.2÷0.6/2÷6

Max external effective gripping force [N]

3-finger parallel grippers

• Wedge hook mechanism for accurate

Double acting

16 20 25 32 40 50 63 80 100 125

4 4 6 8 8 12 16 20 24 32

Anodized aluminium

Carbon steel

0.1÷0.6/1÷6



TPF

- 2-finger parallel grippers
- Compact design, light weight and rugged construction.
- SCM cam
- Optimized positioning bottom hole for accurate installation.
- Designed for long soft-jaws installation.

TPF	Values/Description							
Technology	Dual-piston with cams							
Acting type	Double acting							
Tube [mm]	12 16 2							
Stroke [mm]	15 20 25							
Operating pressure range [MPa]/[bar]		0.2÷0.7/2÷7						
Max external effective gripping force [N]		60						
Body	Hard anodized aluminium							
Fingers / Jaws	Aluminium							
Magnet		Yes						

parallel grippers | 2-finger

TPG

- 2-finger parallel grippers
- Compact design.
- Robust T-rail guide construction.
- Can reach high torques suitable for long jaws design.
- Oval piston-driven design ensures maximum gripping force. Dust-proof module can prevent foreign
- matters (>0.5 mm) entering the gripper.
- Sensor switch or proximity sensor are

TPG	Values/Description										
Technology	Wedge hook, Oval piston										
Acting type	Double acting										
Size	50	66	80	100	125	160	200	300			
Stroke[mm]	4	6	8	10	12	16	20	30			
Operating pressure range [MPa]/[bar]				0.3÷0	.8/3÷8						
Max external effective gripping force [N]				34	111						
Body	Hard anodized aluminium alloy										
Fingers / Jaws			Carbo	n steel.	Hard an	odized					
Magnet				Y	es						

TPM

3-finger parallel grippers

- Compact design.
- Robust T-rail.
- Can reach maximum torque suitable for long jaws design.

• Dust-proof module can prevent foreign matters (>0.5 mm) entering the gripper.

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М		,	Values/De	escription	1				
hnology	Wedge hook								
ting type	Double acting								
pe [mm]	50	66	80	100	125	160			
oke [mm]	4	6	8	10	12	16			
erating pressure range [MPa]/[bar]	0.2÷0.8/2÷8								
x external effective gripping force [N]			17	47					
dy		Hard	anodized	aluminiun	n alloy				
gers / Jaws			Carbo	n steel					
gnet			Y	es					
x external effective gripping force	measur	ed for th	ne larges	t bore, g	gripping	length			

ТРМ	Values/Description									
Technology			Wedg	je hook						
Acting type	Double acting									
Tube [mm]	50	66	80	100	125	160				
Stroke [mm]	4	6	8	10	12	16				
Operating pressure range [MPa]/[bar]	0.2÷0.8/2÷8									
Max external effective gripping force [N]			1	747						
Body		Hard	anodized	aluminiur	n alloy					
Fingers / Jaws			Carbo	on steel						
Magnet	Yes									
Max external effective gripping force	measu	red for th	ne larges	st bore, g	gripping	length				

